

# Tempered distributions

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**Intended readers:** At roughly the level of a first-year graduate student of mathematics.

**Specific prerequisites include** parts 1 and 2 of my notes on Fourier transforms, and some introductory graduate-level analysis

**Feedback:** If you find this useful, or if you have comments or suggestions, or if you just want to say hello, I would very much enjoy hearing from you: cborgers@tufts.edu.

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## 1 Purpose of these notes

This is *not* a comprehensive introduction to tempered distributions, but just a brief review of what tempered distributions are. I have added some intuition and motivation that had not previously been entirely clear to me.

All functions in these notes are assumed to be defined on  $\mathbb{R}$ , with values in  $\mathbb{C}$ . We write:

$$\mathcal{D} = C_c^\infty \quad \text{and} \quad \mathcal{S} = \text{Schwartz space.}$$

A *distribution* is a continuous linear functional on  $\mathcal{D}$ . The motivation is as follows. A locally integrable function  $f = f(x)$  can be identified with the linear functional

$$F_f: \mathcal{D} \rightarrow \mathbb{C}, \quad (1)$$

$$\varphi \mapsto \int_{-\infty}^{\infty} f(x) \varphi(x) dx. \quad (2)$$

Knowing  $F_f$ , we can back out  $f$ . I'll very briefly review why this is so shorty. But there are also linear functionals on  $\mathcal{D}$  that don't come from functions. The most famous example is

$$\varphi \mapsto \varphi(0).$$

Another interesting example is

$$\varphi \mapsto \lim_{r \rightarrow \infty} \int_{-r}^r \frac{\varphi(x)}{x} dx.$$

Distributions offer a way of viewing these examples as generalized functions.

If  $\mathcal{D}$  is replaced by  $\mathcal{S}$ , one obtains the notion of *tempered distributions*. Then local integrability is no longer sufficient to guarantee the existence of the integrals  $\int_{-\infty}^{\infty} f(x) \varphi(x) dx$ . One has to assume also that  $f(x)$  does not grow too fast as  $x \rightarrow \pm\infty$ . I will discuss this, and I will discuss the reason *why* one might want to replace  $\mathcal{D}$  by  $\mathcal{S}$ , and whether one might be able to make choices other than  $\mathcal{D}$  or  $\mathcal{S}$ .

The notion of *continuity* of linear functionals that is used here is extremely weak, so weak that it is hard to find examples of linear functionals that are *not* continuous. Why this continuity requirement is needed at all will be discussed later in these notes; initially, it isn't needed.

## 2 Locally integrable functions as linear functionals on $\mathcal{D}$

**Definition 1.** A measurable function  $f: \mathbb{R} \rightarrow \mathbb{C}$  is called *locally integrable* if for all real  $a$  and  $b$  with  $a < b$ ,  $f \cdot 1_{[a,b]} \in L^1$ . The vector space of all locally integrable functions is denoted by  $L^1_{\text{loc}}$ .

**Theorem 1.** If  $\psi \in \mathcal{D}$  has integral 1, and if  $\psi_\varepsilon(x) = \frac{1}{\varepsilon} \psi\left(\frac{x}{\varepsilon}\right)$  for  $\varepsilon > 0$ , then

$$\forall f \in L^1_{\text{loc}} \quad f(x) = \lim_{\varepsilon \rightarrow 0^+} \int_{-\infty}^{\infty} f(y) \psi_\varepsilon(x-y) dy \quad \text{for almost all } x.$$

This is a well-known fact of analysis. It follows from the Lebesgue differentiation theorem:

**Lebesgue differentiation theorem.** Let  $f \in L^1_{\text{loc}}$ . Then

$$f(x) = \lim_{\varepsilon \rightarrow 0^+} \frac{1}{2\varepsilon} \int_{x-\varepsilon}^{x+\varepsilon} f(y) dy \quad \text{for almost all } x.$$

Theorem 1 implies that the linear functional  $F_f$  (see eqs. (1), (2)) determines the function  $f$  almost everywhere. (Of course, "almost everywhere" is the best one can expect. After all,  $f$  is only *defined* almost everywhere.)

### 3 Locally integrable, polynomially growing functions as linear functionals on $\mathcal{S}$

**Definition 2.** A function  $f \in L^1_{\text{loc}}$  is called polynomially growing if there exists an  $n \in \mathbb{N}$  and a constant  $C > 0$  so that

$$\limsup_{|x| \rightarrow \infty} |f(x)| \leq C|x|^n.$$

The space of all such functions is denoted by  $L^1_{\text{loc,poly}}$ .

**Theorem 2.** If  $\psi \in \mathcal{S}$  has integral 1, and if  $\psi_\varepsilon(x) = \frac{1}{\varepsilon} \psi\left(\frac{x}{\varepsilon}\right)$  for  $\varepsilon > 0$ , then

$$\forall f \in L^1_{\text{loc,poly}} \quad f(x) = \lim_{\varepsilon \rightarrow 0^+} \int_{-\infty}^{\infty} f(y) \psi_\varepsilon(x-y) dy \quad \text{for almost all } x.$$

This, too, follows from the Lebesgue differentiation theorem: It implies that the linear functional

$$\begin{aligned} F_f: \mathcal{S} &\rightarrow \mathbb{C}. \\ \varphi &\mapsto \int_{-\infty}^{\infty} f(x) \varphi(x) dx \end{aligned}$$

determines the function  $f$  almost everywhere. The assumption of (at most) polynomial growth is needed to ensure that the integrals  $\int_{-\infty}^{\infty} f(x) \varphi(x) dx$ ,  $\varphi \in \mathcal{S}$ , exist.

## 4 How about domains other than $\mathcal{D}$ and $\mathcal{S}$ ?

One could consider other spaces on which to study linear functionals. I will think a bit about possible subspaces  $\mathcal{V} \subseteq \mathcal{S}$  other than  $\mathcal{D}$  and  $\mathcal{S}$ . The functions in  $\mathcal{V}$  are called *test functions* in this context.

**Notation:**

$\mathcal{V}^* = \text{space of linear functionals } \mathcal{V} \rightarrow \mathbb{C} \text{ (without any continuity condition)}$

In light of Theorem 2, one might consider taking  $\mathcal{V}$  to be the much smaller space

$$\mathcal{G} = \text{span} \left\{ e^{-(x-\mu)^2/(2\sigma^2)} : \mu \in \mathbb{R}, \sigma > 0 \right\}$$

for instance. The space  $L^1_{\text{loc,poly}}$  is embedded in  $\mathcal{G}^*$ , in the sense that the functional

$$\varphi \mapsto \int_{-\infty}^{\infty} f(x)\varphi(x) dx$$

determines the function  $f$  almost everywhere if  $f \in L^1_{\text{loc,poly}}$ . Actually,  $f$  could even be something like  $e^x$  here, which grows faster than polynomially as  $x \rightarrow \infty$ . Reducing the domain,  $\mathcal{V}$ , of the linear functionals can broaden the space of functions that can be viewed as embedded in  $\mathcal{V}^*$ .

## 5 Derivatives of linear functionals

**Definition 3.** Let  $\mathcal{V} \subseteq \mathcal{S}$  be a subspace that is invariant under differentiation:

$$\forall \varphi \in \mathcal{V} \quad \varphi' \in \mathcal{V}.$$

Let  $F \in \mathcal{V}^*$ . The derivative of  $F$  is the linear functional  $F' \in \mathcal{V}^*$  defined by

$$\langle F', \varphi \rangle = -\langle F, \varphi' \rangle.$$

This is motivated by integration by parts.

Evidently  $\mathcal{D}$  and  $\mathcal{S}$  are invariant under differentiation, whereas  $\mathcal{G}$  is not. Derivatives of linear functionals on  $\mathcal{G}$  are not well-defined. However, the following larger spaces are invariant under differentiation:

$$\mathcal{H} = \text{span} \left\{ x^n e^{-(x-\mu)^2/(2\sigma^2)} : n \in \mathbb{N} \cup \{0\}, \mu \in \mathbb{R}, \sigma > 0 \right\},$$

and

$$\mathcal{I} = \text{span} \left\{ x^n e^{-(x-\mu)^2/(2\sigma^2)} : n \in \mathbb{N} \cup \{0\}, \mu \in \mathbb{C}, \sigma > 0 \right\}.$$

Linear functionals in  $\mathcal{D}^*$ ,  $\mathcal{S}^*$ ,  $\mathcal{H}^*$ ,  $\mathcal{I}^*$  can be differentiated infinitely often.

## 6 Fourier transforms of linear functionals

**Definition 4.** Let  $\mathcal{V} \subseteq \mathcal{S}$  be a subspace that is invariant under Fourier transform:

$$\forall \varphi \in \mathcal{V} \quad \hat{\varphi} \in \mathcal{V}.$$

Let  $F \in \mathcal{V}^*$ . The Fourier transform of  $F$  is the linear functional  $\hat{F} \in \mathcal{V}^*$  defined by

$$\langle \hat{F}, \varphi \rangle = \langle F, \hat{\varphi} \rangle.$$

This is motivated by the symmetry property of the Fourier transform on  $L^1$ .

**Theorem 3.**  $\mathcal{D} = C_c^\infty$  is not invariant under Fourier transform. Much more strongly:

$$\varphi \in \mathcal{D} - \{0\} \Rightarrow \hat{\varphi} \notin \mathcal{D}.$$

This is the reason why  $\mathcal{D}$  is not a good domain for distributions when one wants to work with Fourier transforms.

*Proof.* Let  $\varphi \in \mathcal{D}$ . Then

$$\hat{\varphi}(t) = \int_{-\infty}^{\infty} \varphi(x) \left( \sum_{k=0}^{\infty} \frac{(ixt)^k}{k!} \right) dx = \int_{-\infty}^{\infty} \sum_{k=0}^{\infty} \varphi(x) \frac{(ix)^k}{k!} t^k dx.$$

The integral and sum can be swapped; this follows for instance from Fubini's theorem. So we obtain

$$\hat{\varphi}(t) = \sum_{k=0}^{\infty} \left( \int_{-\infty}^{\infty} \varphi(x) \frac{(ix)^k}{k!} dx \right) t^k.$$

This shows that  $\hat{\varphi}$  is analytic. It therefore cannot vanish on an interval unless it vanishes everywhere.  $\square$

It is advantageous to keep the domain of the linear functionals small. For instance, I noted earlier that the space of functions that can be thought of as elements of  $\mathcal{V}^*$  may be larger for smaller  $\mathcal{V}$ . To obtain a small space that is invariant under Fourier transform, starting with  $\mathcal{D}$ , we might add  $\mathcal{F}[\mathcal{D}]$ . We define

$$\mathcal{R} = \mathcal{D} + \mathcal{F}[\mathcal{D}].$$

**Theorem 4.**

space	invariant under differentiation?	invariant under Fourier transform?
$\mathcal{D}$	✓	✗
$\mathcal{R}$	✓	✓
$\mathcal{G}$	✗	✗
$\mathcal{H}$	✓	✗
$\mathcal{I}$	✓	✓
$\mathcal{S}$	✓	✓

*Proof.* (1) It is clear that  $\mathcal{D}$  is invariant under differentiation. We know from Theorem 3 that it is not invariant under Fourier transform.

(2) We will next show that  $\mathcal{D} + \mathcal{F}[\mathcal{D}]$  is invariant under differentiation. Since  $\mathcal{D}$  is invariant under differentiation, it suffices to show that the derivative of a function in  $\mathcal{F}[\mathcal{D}]$  belongs to  $\mathcal{F}[\mathcal{D}]$ . So let  $\psi \in \mathcal{D}$  and  $\varphi = \mathcal{F}[\psi] = \hat{\psi}$ . Then

$$\varphi'(t) = \int_{-\infty}^{\infty} \psi(x) ix e^{ixt} dx,$$

which is the Fourier transform of  $ix\psi(x) \in \mathcal{D}$ . To show that  $\mathcal{D} + \mathcal{F}[\mathcal{D}]$  is invariant under Fourier transform, note that the Fourier transform of a function in  $\mathcal{D}$  is in  $\mathcal{F}[\mathcal{D}]$ , and the Fourier transform of  $\mathcal{F}[\mathcal{D}]$  is, by the inversion theorem, in  $\mathcal{D}$ .

(3) Clearly  $\mathcal{G}$  is not invariant under differentiation. It is not invariant under Fourier transform either. For instance,

$$\begin{aligned} \mathcal{F}\left[e^{-(x-1)^2}\right] &= \int_{-\infty}^{\infty} e^{-(x-1)^2} e^{ixt} dx = e^{it} \int_{-\infty}^{\infty} e^{-(x-1)^2} e^{i(x-1)t} dx = \\ &e^{it} \int_{-\infty}^{\infty} e^{-x^2} e^{ixt} dx = \int_{-\infty}^{\infty} e^{-(x-it/2)^2} dx e^{-t^2/4} e^{it} = \sqrt{\pi} e^{-t^2/4} e^{it} \notin \mathcal{G}. \end{aligned}$$

(Justification of the last equation involves contour integration.)

(4)  $\mathcal{H}$  is obviously invariant under differentiation, but it isn't invariant under Fourier transform either:

$$\mathcal{F}\left[e^{-(x-1)^2}\right] = \sqrt{\pi} e^{-t^2/4} e^{it} \notin \mathcal{H}.$$

(5)  $\mathcal{I}$  is obviously invariant under differentiation as well. To prove that it is also invariant under Fourier transform, we must show that the Fourier transform of

$$\varphi(x) = x^n e^{-(x-\mu)^2/(2\sigma^2)},$$

where  $n \in \mathbb{N} \cup \{0\}$ ,  $\mu \in \mathbb{C}$ , and  $\sigma > 0$ , belongs to  $\mathcal{I}$ . We have

$$\hat{\varphi}(t) = \int_{-\infty}^{\infty} x^n e^{-(x-\mu)^2/(2\sigma^2)} e^{ixt} dx = (-i)^n \frac{d^n}{dt^n} \int_{-\infty}^{\infty} e^{-(x-\mu)^2/(2\sigma^2)} e^{ixt} dx.$$

Since  $\mathcal{I}$  is invariant under differentiation, it suffices now to prove that

$$\int_{-\infty}^{\infty} e^{-(x-\mu)^2/(2\sigma^2)} e^{ixt} dx \in \mathcal{I}.$$

We write this as

$$\int_{-\infty}^{\infty} e^{-\left(\frac{x^2}{2\sigma^2} - \frac{\mu x}{\sigma^2} - ixt + \frac{\mu^2}{2\sigma^2}\right)} dx \in \mathcal{I}.$$

Complete the square:

$$\begin{aligned} \frac{x^2}{2\sigma^2} - \frac{\mu x}{\sigma^2} - ixt + \frac{\mu^2}{2\sigma^2} &= \frac{1}{2\sigma^2} (x^2 - 2\mu x - 2\sigma^2 ixt + \mu^2) = \\ \frac{1}{2\sigma^2} \left[ (x - (\mu + \sigma^2 it))^2 + \mu^2 - (\mu + \sigma^2 it)^2 \right] &= \frac{1}{2\sigma^2} \left[ (x - (\mu + \sigma^2 it))^2 - 2\mu\sigma^2 it + \sigma^4 t^2 \right] = \\ \frac{(x - (\mu + \sigma^2 it))^2}{2\sigma^2} - \mu it + \frac{\sigma^2 t^2}{2}. \end{aligned}$$

So

$$\int_{-\infty}^{\infty} e^{-\left(\frac{x^2}{2\sigma^2} - \frac{\mu x}{\sigma^2} - ixt + \frac{\mu^2}{2\sigma^2}\right)} dx = e^{-\frac{\sigma^2 t^2}{2} + \mu it} \int_{-\infty}^{\infty} e^{-\frac{(x - (\mu + \sigma^2 it))^2}{2\sigma^2}} dx. \quad (3)$$

Using contour integration, and a change of variables, the integral is seen to equal  $\sqrt{2\pi\sigma^2}$ . Altogether, (3) becomes

$$\sqrt{2\pi\sigma^2} e^{-\frac{\sigma^2 t^2}{2} + \mu it} \in \mathcal{I}.$$

(6)  $\mathcal{S}$  is invariant under differentiation and Fourier transform; see the second part of my notes on the Fourier transform.  $\square$

So differentiation and Fourier transforms can be defined on  $\mathcal{R}^*$  or on  $\mathcal{I}^*$ . The space  $L^1_{\text{loc,poly}}$  can be thought of as a subspace of both  $\mathcal{R}^*$  and  $\mathcal{I}^*$ . More functions than those in  $L^1_{\text{loc,poly}}$  can be thought of as elements of  $\mathcal{I}^*$  — for instance, the function  $e^x$ . Interestingly,  $\mathcal{R}$  and  $\mathcal{I}$  have no non-zero elements in common:

**Theorem 5.**  $\mathcal{R} \cap \mathcal{I} = \{0\}$ .

*Proof.* Suppose  $\varphi \in \mathcal{I}$  can be written in the form

$$\varphi = \psi + \hat{\eta}$$

where  $\psi \in \mathcal{D}$  and  $\hat{\eta} \in \mathcal{D}$ . All elements of  $\mathcal{I}$  are analytic functions. Also,  $\hat{\eta}$  is analytic; see the proof of Theorem 3. Therefore

$$\psi = \varphi - \hat{\eta}$$

is analytic. Since  $\psi$  is zero outside a compact interval,  $\psi = 0$ . So

$$\varphi = \hat{\eta}.$$

By the inversion formula,

$$\hat{\varphi} = \hat{\eta} = 2\pi\eta(-x).$$

Since  $\mathcal{I}$  is invariant under Fourier transform, this implies  $2\pi\eta(-x) \in \mathcal{I}$ , so  $\eta \in \mathcal{I}$ . Therefore  $\eta$  is both analytic, and has compact support, therefore  $\eta = 0$ , and hence  $\varphi = 0$ .  $\square$

## 7 Convolving linear functionals with test functions

**Definition 5.** Let  $\mathcal{V}$  be a subspace of  $\mathcal{S}$ . Assume

$$\forall \varphi \in \mathcal{V} \quad \forall x \in \mathbb{R} \quad \varphi(x - \cdot) \in \mathcal{V}. \quad (4)$$

Let  $F \in \mathcal{V}^*$  and  $\varphi \in \mathcal{V}$ . The convolution  $F * \varphi$  is the function

$$(F * \varphi)(x) = \langle F(y), \varphi(x - y) \rangle. \quad (5)$$

I wrote " $F(y)$ " in (5) to indicate that  $F$  is acting on  $\varphi(x - y)$  thought of as a function of  $y$ , with  $x$  fixed.

The spaces  $\mathcal{D}$ ,  $\mathcal{R}$ ,  $\mathcal{I}$ , and  $\mathcal{S}$  all satisfy the condition (4).

## 8 The first place where continuity matters: smoothness of convolutions

Let's try to prove differentiability of  $F * \varphi$ . We have

$$\frac{\langle F(y), \varphi(x + h - y) \rangle - \langle F(y), \varphi(x - y) \rangle}{h} = \left\langle F(y), \frac{\varphi(x + h - y) - \varphi(x - y)}{h} \right\rangle.$$

The functions

$$\frac{\varphi(x + h - y) - \varphi(x - y)}{h}, \quad y \in \mathbb{R},$$

with  $x$  fixed, converge, as  $h \rightarrow 0$ , to  $\varphi'(x - y)$ . This is obviously valid pointwise, but it is valid also in a much stronger sense, to be discussed momentarily. To conclude that  $F * \varphi$  is differentiable, we'd like to say now that

$$\lim_{h \rightarrow 0} \left\langle F(y), \frac{\varphi(x + h - y) - \varphi(x - y)}{h} \right\rangle = \left\langle F(y), \lim_{h \rightarrow 0} \frac{\varphi(x + h - y) - \varphi(x - y)}{h} \right\rangle = \langle F(y), \varphi'(x - y) \rangle.$$

For this to be valid, we need a continuity condition on  $F$ .

**Definition 6.** A sequence  $\{\varphi_k\}_{k \in \mathbb{N}}$  of Schwartz functions converges to 0 in  $\mathcal{S}$  if

$$\forall \alpha \in \mathbb{N} \cup \{0\} \quad \forall \beta \in \mathbb{N} \cup \{0\} \quad \lim_{k \rightarrow \infty} \left\| x^\alpha \frac{d^\beta \varphi_k}{dx^\beta} \right\|_\infty = 0 \quad (6)$$

A sequence  $\{\varphi_k\}_{k \in \mathbb{N}}$  of functions in  $\mathcal{S}$  converges to  $\lambda \in \mathcal{S}$  if the sequence  $\{\varphi_k - \lambda\}_{k \in \mathbb{N}}$  converges to zero in  $\mathcal{S}$ .

**Lemma 1.** As  $h \rightarrow 0$ , the functions

$$\frac{\varphi(x+h-y) - \varphi(x-y)}{h}$$

(understood as functions of  $y$ , with  $x$  fixed) converge to  $\varphi'(x-y)$  in  $\mathcal{S}$ .

*Proof.* This is straightforward. As an example, I'll spell out the proof that (for a fixed  $x$ )

$$\lim_{h \rightarrow 0} \left\| y \frac{d}{dy} \left( \frac{\varphi(x+h-y) - \varphi(x-y)}{h} - \varphi'(x-y) \right) \right\|_\infty = 0.$$

Let  $x \in \mathbb{R}$  and  $y \in \mathbb{R}$ . Let  $|h| \leq 1$ . Then

$$\begin{aligned} & \left| y \frac{d}{dy} \left( \frac{\varphi(x+h-y) - \varphi(x-y)}{h} - \varphi'(x-y) \right) \right| \\ &= |y| \left| \frac{\varphi'(x+h-y) - \varphi'(x-y)}{h} - \varphi''(x-y) \right| = \\ &= |y| |\varphi''(x+ch-y) - \varphi''(x-y)| \quad (\text{for some } c \in (0, 1)) \\ &= |y| \varphi'''(x+cdh-y) |h| \quad (\text{for some } d \in (0, 1)) \\ &\leq (|(x+cdh-y) \varphi'''(x+cdh-y)| + |(x+cdh) \varphi'''(x+cdh-y)|) |h| \\ &\leq (\|s \varphi'''(s)\|_\infty + (|x|+1) \|\varphi'''(s)\|_\infty) |h|. \end{aligned}$$

(In the last step, I used that  $|h| \leq 1$ . I used the letter  $s$  for the independent variable because  $x$  and  $y$  are taken.) So

$$\begin{aligned} & \left\| y \frac{d}{dy} \left( \frac{\varphi(x+h-y) - \varphi(x-y)}{h} - \varphi'(x-y) \right) \right\|_\infty \leq \\ & \quad (\|s \varphi'''(s)\|_\infty + (|x|+1) \|\varphi'''(s)\|_\infty) |h|. \end{aligned}$$

This tends to zero as  $h \rightarrow 0$ . □

**Definition 7.** Let  $\mathcal{V} \subseteq \mathcal{S}$  be a subspace. A linear functional  $F \in \mathcal{V}^*$  is called a distribution on  $\mathcal{V}$  if it is continuous in the sense that  $\varphi_k \rightarrow 0$  in  $\mathcal{S}$  (in the sense of Definition 6) implies  $F(\varphi_k) \rightarrow 0$ . The space of all continuous linear functionals on  $\mathcal{V}$  is denoted by  $\mathcal{V}'$ .

The distributions on  $\mathcal{S}$  are called tempered distributions.

Definition 6 describes an extremely strong notion of convergence. Since the notion of convergence in  $\mathcal{S}$  is so strong, the notion of continuity is extremely weak. It is, however, sufficient for our purposes. We conclude from the preceding discussion:

**Theorem 6.** Let  $\mathcal{V} \subseteq \mathcal{S}$  be a subspace that is invariant with respect to differentiation.

Assume

$$\forall \varphi \in \mathcal{V} \quad \forall x \in \mathbb{R} \quad \varphi(x - \cdot) \in \mathcal{V}.$$

Let  $F \in \mathcal{V}'$  and  $\varphi \in \mathcal{V}$ . Then

$$\frac{d}{dx}(F * \varphi)(x) = (F * \varphi')(x),$$

and consequently more generally

$$\frac{d^k}{dx^k}(F * \varphi)(x) = F * \frac{d^k \varphi}{dx^k}(x)$$

for all  $k \geq 0$ . In particular,  $F * \varphi \in C^\infty$ .

## 9 A discontinuous linear functional on the Schwartz space

Here is a fairly artificial and non-explicit construction of a linear functional on  $\mathcal{S}$  that is not continuous. Let  $(b_i)_{i \in I}$  be a Hamel basis of  $\mathcal{S}$ . Let  $\varphi_1, \varphi_2, \dots \in \mathcal{S}$  with  $\varphi_k = b_{i_k}$ ,  $i_k \in I$ , and the  $i_k$  are different from each other. By scaling the  $\varphi_k$ , we can assume without loss of generality that

$$\forall \alpha \in \{0, 1, \dots, k\} \quad \forall \beta \in \{0, 1, \dots, k\} \quad \left\| x^\alpha \frac{d^\beta \varphi_k}{dx^\beta} \right\|_\infty \leq \frac{1}{k}.$$

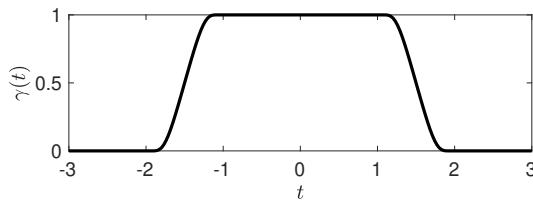
Then clearly  $\varphi_k \rightarrow 0$  in  $\mathcal{S}$ . Now define a linear functional  $F$  on  $\mathcal{S}$  by  $F(\varphi_k) = 1$ , and  $F(b_i) = 0$  if  $b_i$  is none of the  $\varphi_k$ . Clearly,  $F$  is not continuous.

## 10 Tempered distributions are limits of functions in $C_c^\infty$

**Theorem 7.** For any  $F \in \mathcal{S}'$ , there exists a sequences  $\eta_1, \eta_2, \dots$  in  $C_c^\infty$  with

$$\forall \varphi \in \mathcal{S} \quad \langle F, \varphi \rangle = \lim_{k \rightarrow \infty} \int_{-\infty}^{\infty} \eta_k(x) \varphi(x) dx. \quad (7)$$

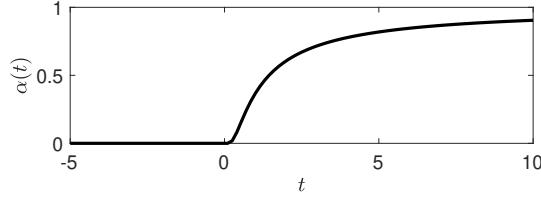
**Sketch of proof.** Make  $F$  smooth by convolving with  $\frac{1}{\varepsilon} \psi\left(\frac{x}{\varepsilon}\right)$  for a small  $\varepsilon > 0$ , where  $\psi \in \mathcal{S}$  with  $\int_{-\infty}^{\infty} \psi(x) dx = 1$ . Then make the support compact by multiplying by  $\gamma(x/R)$  for a large  $R$ , where  $\gamma(x) = 1$  for  $|x| \leq 1$ ,  $\gamma(x) = 0$  for  $|x| \geq 2$ , and  $\gamma$  is monotonic in  $[-2, -1]$  and in  $[1, 2]$ .



□

Here is a way of constructing  $\gamma$ . We start with

$$\alpha(t) = \begin{cases} 0 & \text{if } t \geq 0, \\ e^{-1/t} & \text{if } t > 0. \end{cases}$$



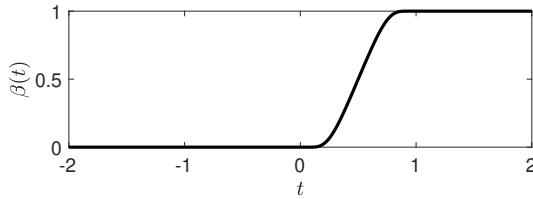
then define

$$\beta(t) = \frac{\alpha(t)}{\alpha(t) + \alpha(1-t)}.$$

Then  $\beta(t) = 0$  for  $t \leq 0$ ,  $\beta(t) = 1$  for  $t \geq 1$ , and  $\beta$  is increasing, since for  $t > 0$  we can write

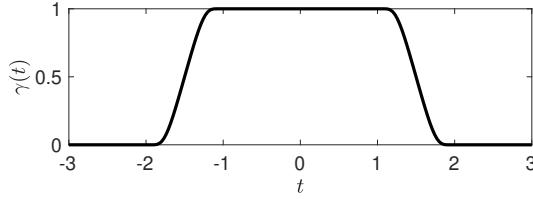
$$\beta(t) = \frac{1}{1 + \alpha(1-t)/\alpha(t)}.$$

( $\alpha(1-t)$  decreases,  $\alpha(t)$  increases, so  $\alpha(1-t)/\alpha(t)$  decreases, and  $\beta$  increases.)



Then define

$$\gamma(t) = \beta(t+2)\beta(-t+2).$$



It is clear that the convergence in (7) cannot be uniform in  $\varphi$ . For instance, think of  $F = 1$ . That's a tempered distribution, and convolving with  $\frac{1}{\varepsilon}\psi\left(\frac{x}{\varepsilon}\right)$  doesn't change it at all. So a function in  $\mathcal{D}$  that approximates  $F$ , in this case, is simply the function  $\gamma(x/R)$  for large  $R$ . That doesn't approximate  $\langle F, \varphi \rangle$  for *all*  $\varphi$ , but it does approximate it well if  $\varphi(x)$  is very close to zero for  $|x| \geq R$ .

## 11 The Fourier transform of $x^2$

The function  $x^2$  is a tempered distribution, which we'll denote by  $F$ . Being a tempered distribution, it has a Fourier transform. And the strangest thing is, that Fourier transform can approximately be thought of as a smooth, compactly supported function.

Why is that, in this example?

$$\langle \hat{F}(t), \varphi(t) \rangle = \langle F(x), \hat{\varphi}(x) \rangle = \int_{-\infty}^{\infty} x^2 \hat{\varphi}(x) dx.$$

Now

$$x^2 \hat{\varphi}(x) = x^2 \int_{-\infty}^{\infty} \varphi(t) e^{itx} dt = - \int_{-\infty}^{\infty} \varphi(t) \frac{d^2}{dt^2} e^{itx} dt = - \int_{-\infty}^{\infty} \varphi''(t) e^{itx} dt.$$

So we can also write

$$\langle \hat{F}(t), \varphi(t) \rangle = - \int_{-\infty}^{\infty} \widehat{\varphi''}(x) dx.$$

This, by the inversion formula, is

$$-2\pi\varphi''(0).$$

Here is the result, in summary. The tempered distribution

$$\varphi \mapsto \int_{-\infty}^{\infty} x^2 \varphi(x) dx$$

has the Fourier transform

$$\varphi \mapsto -2\pi\varphi''(0).$$

To approximate this by a smooth function, we convolve it with

$$\psi_{\varepsilon}(x) = \frac{e^{-(x/\varepsilon)^2}}{\varepsilon\sqrt{\pi}}$$

for a small  $\varepsilon > 0$ . We obtain

$$\langle \hat{F}(s), \psi_\varepsilon(t-s) \rangle = -2\pi \psi_\varepsilon''(t) = \frac{4\sqrt{\pi}}{\varepsilon^3} \left(1 - \frac{2}{\varepsilon^2} t^2\right) e^{-(t/\varepsilon)^2}.$$

In summary:

*The Fourier transform of the function  $x^2$ , mollified by convolving with*

$$\psi_\varepsilon(x) = \frac{e^{-(x/\varepsilon)^2}}{\varepsilon\sqrt{\pi}},$$

$\varepsilon > 0$ , *equals*

$$\frac{4\sqrt{\pi}}{\varepsilon^3} \left(1 - \frac{2}{\varepsilon^2} t^2\right) e^{-t^2/\varepsilon^2}.$$

